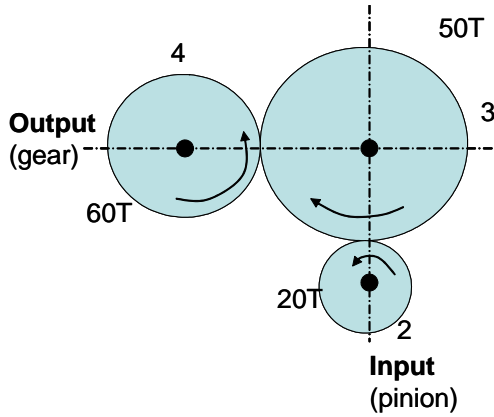


Gear Design



Problem: Pinion 2 is shown in the figure runs at 1750 rpm and transmits 2.5 kW to idler gear 3. The teeth are cut on the 20° full-depth system and have a module of $m = 2.5$ mm.

a) Draw a free-body diagram of gear 3 and show all the forces and compute the torques on the output gear 4

$$T = W_t * \frac{d_p}{2}$$

W_t : tangential force

d_p : pitch diameter

$$H = T * \omega$$

H: Power

ω : angular rotation

$$H = W_t * \frac{d_p}{2} * \left(\frac{2\pi}{60} * \omega_2 \right)$$

$$\omega \text{ (rev/min)} = \frac{\omega}{60} \text{ (rev/sec)} = 2\pi \frac{\omega}{60} \text{ (rad/sec)}$$

$$H = \frac{d_p \pi * \omega_2 * W_t}{60 * 10^3}$$

where, H : (kN)

ω_2 : (rev/min)

d_p : (mm)

W_t : (kN)

$$W_t = \frac{60 * 10^3 * H}{\pi d_p * \omega_2}$$

$d_p = N * m$:

N: number of teeth

m: module (mm)

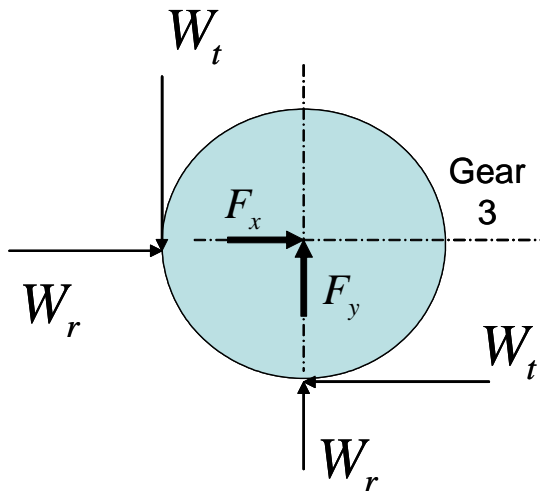
$$W_t = \frac{60 * 10^3 * H}{\pi (N * m) * \omega_2}$$

$$W_t = \frac{60 * 10^3 * (2.5)}{\pi (20 * 2.5) * 1750} = 0.546 \text{ kN}$$

Thus, the tangential force of gear 2 on gear 3 is 0.546 kN. The radial force is;

$$W_r = W_t * \tan 20^\circ = 0.546 * \tan 20^\circ = 0.199 \text{ kN}$$

The tangential reaction of gear 4 on gear 3 is also equal to W_t



Forces on shaft of gear 3;

$$F_x = - (-0.546 + 0.199) = 0.347 \text{ kN}$$

$$F_y = - (0.199 - 0.546) = 0.347 \text{ kN}$$

The output Torque:

$$\frac{\omega_4}{\omega_2} = \frac{r_2}{r_4} = \frac{N_2}{N_4}$$

$$\frac{N_2}{N_4} = \left(-\frac{N_2}{N_3}\right) * \left(-\frac{N_3}{N_4}\right) = \frac{20}{60}$$

$$T_2 = W_t * r_2$$

$$T_4 = W_t * r_4$$

$$T_4 = \frac{r_4}{r_2} * T_2 = \frac{N_4}{N_2} * T_2$$

$$T_4 = \frac{60}{20} * T_2 = 3 * (0.546 * \frac{50}{2})$$

$$T_2 = 13.65 \text{ Nm}$$

$$T_4 = 40.95 \text{ Nm}$$

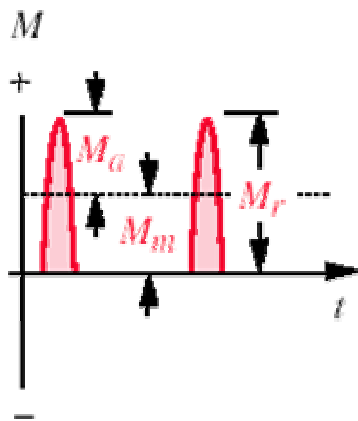
b) Compute the mean and alternating loads on 1) pinion, 2) gear and, 3) idler.

The repeated loads on pinion and gear:

$$R = 0 = \frac{\sigma_{\min}}{\sigma_{\max}} \quad (\text{since } \sigma_{\min} = 0)$$

$$W_{t_{\text{mean}}} = \frac{W_t}{2} = \frac{0.546}{2} = 0.273 \text{ kN}$$

$$W_{t_{\text{alternating}}} = \frac{W_t}{2} = \frac{0.546}{2} = 0.273 \text{ kN}$$



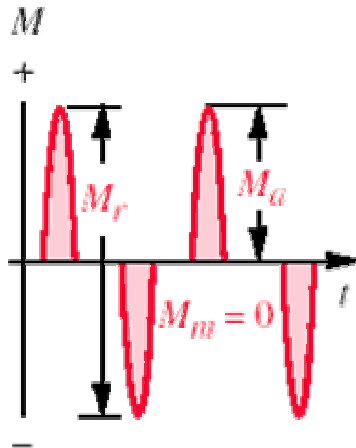
The fully-reversed loads on the idler:

$$R = -1 = \frac{\sigma_{\min}}{\sigma_{\max}}$$

$$|\sigma_{\min}| = |\sigma_{\max}|$$

$$W_{t_{alternating}} = W_t = 0.546 \text{ kN}$$

$$W_{t_{mean}} = 0 \text{ kN}$$



c) Determine a suitable face width and the bending stresses in the idler gear (“3”)

$$\sigma_b = \frac{W_t * P_d}{F * J} * \frac{K_a * K_m}{K_v} * K_S * K_B * K_I$$

Recommended face-width range is

$$\frac{\delta}{P_d} < F < \frac{16}{P_d}$$

$P_d = \text{diametral pitch} = 25.4/m$

Take $F = \frac{12}{P_d}$

$$\frac{8m}{25.4} < F < \frac{16m}{25.4} \quad (\text{SI units})$$

The relation between P_d (U.S. specification) and the module “m” (S.I. unit) is

$$m = \frac{25.4}{P_d} = 2.5 \text{ mm/teeth}$$

Hence, $P_d = 10.16 \text{ teeth/inches}$.

The face width (F):

$$F = \frac{12}{10.16} = 1.81 \text{ inches} = 3 \text{ cm} = 30 \text{ mm}$$

The load distribution factor (K_m)

Using Table 11 – 16

$$K_m = 1.6 \quad (\text{for } F = 1.81 \text{ inches} = 30 \text{ mm})$$

The application factor:

$$K_a = 1 \quad (\text{assume uniform loading; table 11 -17})$$

The velocity factor:

$$K_v = \left(\frac{A}{A + \sqrt{200 * V_t}} \right)^B$$

V_t : pitch-line velocity

$$V_t = \frac{d_p}{2} * \omega = \frac{d_3}{2} * \omega_3$$

Gear 3:

$$d_3 = m N_3 = 2.5 * 50 = 125 \text{ mm}$$

$$\omega_3 = \frac{N_2}{N_3} * \omega_2$$

$$\omega_3 = \frac{20}{50} * 1750$$

$$\omega_3 = 700 \text{ rpm} * \frac{\text{rev}}{\text{min}}$$

$$\omega_3 = 700 * \frac{2\pi}{60} = 73.266 \text{ rad/sec}$$

$$V_t = 4.58 \text{ m/s} = 274.76 \text{ m/min}$$

$$\text{Note that } V_t (\text{ft} / \text{min}) = V_t (\text{m} / \text{sec}) * 196.85$$

$$\text{since } 1 \text{ ft} = 12 \text{ inches} = 30.48 \text{ cm}$$

$$V_t = 901.5 \text{ ft/min}$$

The quality index (Q_v)

Using Table 11-7 (page 710)

V_t	Q_v
0- 800	6-8
901.5 ft/min	?
800-2000	8-10

Take $Q_v = 8$

$$B = \frac{(12 - 8)^{2/3}}{4} = 0.63$$

$$A = 50 + 56(1 - B) = 70.72$$

$$K_v = \left(\frac{70.72}{70.72 + \sqrt{200 * 4.58}} \right)^{0.63} = 0.8$$

The size factor $K_S=1$ for all gears

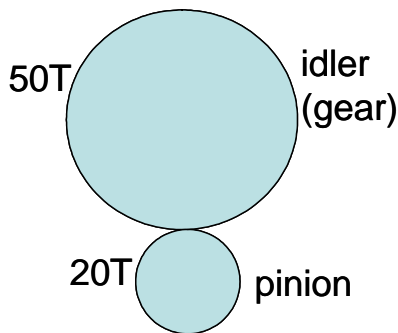
The rim thickness factor $K_B= 1$ (assume no rim)

The idler factor $K_I= 1$ for gears “2” and “4”, $K_I= 1.42$ for the gear “3”.

The bending geometry factor J for 20° presume angle (full depth teeth with HPSTC loading)

pinion : 20 T (20°)
 gear : 60 T (20°)
 idler : 50 T (20°)

First, calculate the J_{pinion} , and J_{gear} based on pinion (gear “2” in the figure) and idler (gear “3” in the figure) interactions:



Using Table 11- 9 (p.716)

$$J_{\text{pinion}} \cong 0.34$$

$$J_{\text{gear(idler)}} \cong 0.39$$

$$\sigma_b = \frac{W_t * P_d}{F * J} * \frac{K_a * K_m}{K_v} * K_S * K_B * K_I$$

$$\text{since } F = \frac{12}{P_d}$$

$$\sigma_b = \frac{W_t * P_d^2}{12J} * \frac{K_a * K_m}{K_v} * K_S * K_B * K_I$$

also,

$$P_d = \frac{25.4}{m}$$

$$\sigma_b = \frac{W_t * \left(\frac{25.4}{m}\right)^2}{12J} * \frac{K_a * K_m}{K_v} * K_S * K_B * K_I$$

$$\sigma_b = \frac{W_t * (53.76)}{m^2 * J} * \frac{K_a * K_m}{K_v} * K_S * K_B * K_I$$

$$m = 2.5 \text{ mm}$$

—————> then σ_b is in MPa

$$W_t = 0.546 \text{ kN}$$

$$\sigma_{b_{pinion}} = \frac{0.546 * (53.76)}{(2.5)^2 * (0.34)} * \frac{1 * 1.6}{0.8} * 1 * 1 * 1$$

$$\sigma_{b_{pinion}} = 27.63 \text{ MPa}$$

$$\sigma_{b_{pinion}} = \frac{0.546 * (53.76)}{(2.5)^2 * (0.39)} * \frac{1 * 1.6}{0.8} * 1 * 1 * 1.42$$

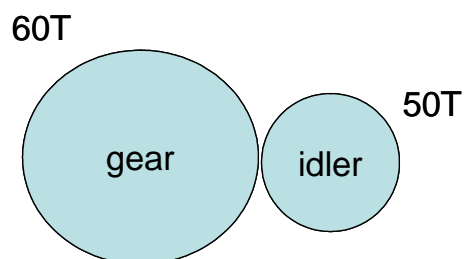
$$\sigma_{b_{gear}} = 34.2 \text{ MPa}$$

Second, calculate the J_{pinion} , and J_{gear} based on idler (“3”) and gear (“4”) interactions:

Using Table 11- 9 (p.716)

$$J_{pinion(idler)} \cong 0.42$$

$$J_{gear} \cong 0.43$$



Note: The idler has a slightly different J factor when considered to be the “gear” in mesh with the smaller pinion (0.42) than when considered to be the “pinion” in mesh with the larger gear (0.43).

$$\sigma_{b_{idler}} = \frac{0.546 * (53.76)}{(2.5)^2 * (0.42)} * \frac{1 * 1.6}{0.8} * 1 * 1 * 1.42$$

$$= 31.75 \text{ MPa}$$

$$\sigma_{b_{gear}} = \frac{0.546 * (53.76)}{(2.5)^2 * (0.43)} * \frac{1 * 1.6}{0.8} * 1 * 1 * 1$$

$$= 21.84 \text{ MPa}$$

d) All gears are made of steel (AGMA grade 2 with Brinell Hardness number of 250 HB). The service life required is 5 years of one-shift operation. Operating temperature is 200⁰ F. Calculate the safety factor for bending stress (Assume 99 % reliability).

$$S_{f_b} = \frac{K_L}{K_T * K_R} * S'_{f_b}$$

$$S'_{f_b} = 280 \text{ MPa} \quad (\text{from the Figure 11-25, pp.733 for HB} = 250)$$

$$\omega_{pinion} = 1750 \text{ rpm}$$

$$\omega_{idler} = 700 \text{ rpm}$$

$$\omega_{gear} = 583.3 \text{ rpm}$$

$$N_{pinion} = 1750 \text{ rpm} * \frac{60 \text{ min}}{\text{hr}} * \frac{2080 \text{ hr}}{\text{shift} - \text{year}} * 5 \text{ yr}$$

$$N_{pinion} = 1.092 * 10^9 \text{ cycles}$$

$$N_{idler} = 0.4368 * 10^9 \text{ cycles}$$

$$N_{\text{gear}} = 0.364 * 10^9 \text{ cycles}$$

The life factor:

$$K_{L(\text{pinion})} = 1.3558 * N^{-0.0178}$$

(Fig. 11-24, $N > 10^8$ commercial app)

$$= 0.936$$

$$K_{L(\text{idler})} = 0.951$$

$$K_{L(\text{gear})} = 0.955$$

The temperature factor:

$$K_T = 1 \quad (T < 250^\circ)$$

The reliability factor:

$$K_R = 1 \quad (\%99 \text{ reliability})$$

$$S_{fb \text{ pinion}} = 262 \text{ MPa}$$

$$N_{b \text{ pinion}} = \frac{262}{27.63} = 9.48$$

$$S_{fb \text{ idler}} = 266 \text{ MPa}$$

$$N_{b \text{ idler}} = \frac{266}{34.2} = 7.77$$

$$S_{fb \text{ gear}} = 267.4 \text{ MPa}$$

$$N_{b \text{ gear}} = \frac{267.4}{21.84} = 12.24$$

Hence, idler is the most critical (it is exposed to fully reversed stresses).

e) Determine the surface stresses for

- 1) pinion- idler mesh
- 2) idler-gear mesh

and the safety factor for surface stresses.

$$\sigma_c = c_p \sqrt{\frac{\omega_t}{F * I * d} \frac{C_a * C_m * C_s * C_f}{C_v}}$$

$$C_a = K_a = 1$$

$$C_m = K_m = 1.6$$

$$C_v = K_v = 0.8$$

$$F = 30 \text{ mm}$$

Notes:

- d (pitch diameter) is the smaller of mating gears
- “T” is the smaller of mating gears
- Be careful with the +/- signs in equations 11.22a and 11.22b.
Eq. 11.22a (+ : external, -: internal)
Eq. 11.22b (- : external, +: internal)

$$C_s = 1 \text{ (size factor)}$$

$$C_f = 1 \text{ (surface finish factor)}$$

The elastic coefficient:

$$C_p = \sqrt{\frac{1}{\pi \left[\left(\frac{1 - \nu_p^2}{E_p} \right) + \left(\frac{1 - \nu_g^2}{E_g} \right) \right]}}$$

All gears are made of steel \longrightarrow $\nu = 0.3$ (Table 11-18 assumes that $\nu = 0.3$)

$$E_p = 30 \cdot 10^6 \text{ psi} = 2 \cdot 10^5 \text{ MPa}$$

Instead of calculating the C_p using the equation; you can directly get the value from the table if the material is available.

			<u>UNIT</u>
pinion	\longrightarrow	steel	
		\longrightarrow	$C_p = 2300$
			$\sqrt{\text{psi}}$
gear	\longrightarrow	steel	
			$C_p = 191$
			$\sqrt{\text{MPa}}$

Surface Geometry Factor (I)

$$I = \frac{\cos \phi}{\left(\frac{1}{\rho_p} \pm \frac{1}{\rho_g} \right) * d_p} \quad \text{use “+” sign for external gears and “-” for internal gears}$$

$$\rho_p = \sqrt{\left(r_p + \frac{1 + x_p}{p_d} \right)^2 - (r_p * \cos \phi)^2} - \frac{\pi}{p_d} * \cos \phi$$

$$\rho_g = c \sin \phi \mp \rho_p \quad \text{-: external gears} \quad \text{+ : internal gears}$$

pinion-idler mesh

$$r_p = \frac{d_p}{2} = \frac{m * N_{pinion}}{2} = \frac{2.5 * 20}{2} = 25 \text{ mm}$$

$$r_{idler} = \frac{d_{idler}}{2} = \frac{2.5 * 50}{2} = \frac{125}{2} \text{ mm}$$

$$\phi = 20^{\circ}$$

$$m = \frac{25.4}{P_d} \longrightarrow P_d = \frac{25.4}{m} = 10.16$$

The pinion addendum coefficient $x_p = 0$
($x_p = 0$ for full-depth teeth and $x_p = 0.25$ for 25 % long-addendum teeth)

$$\rho_p = \sqrt{\left(25 + \frac{1}{10.16}\right)^2 - (25 * \cos 20^{\circ})^2} - \frac{\pi}{10.16} * \cos 20^{\circ}$$

$$\rho_p = 8.54 \text{ mm}$$

$$\rho_{gear} = c \sin \phi - \rho_1 = \left(25 + \frac{125}{2}\right) * \sin 20^{\circ} - 8.54$$

$$\rho_{gear} = 21.39 \text{ mm}$$

$$I = \frac{\cos \phi}{\left(\frac{1}{\rho_p} + \frac{1}{\rho_g}\right) * d_p} = 0.115$$

Idler –gear mesh

idler

$$r_p = \frac{125}{2} m$$

$$r_p = \frac{150}{2} mm$$

$$\phi = 20^{\circ}$$

$$\rho_p = \sqrt{\left(62.5 + \frac{1}{10.16}\right)^2 - (62.5 * \cos 20^\circ)^2} - \frac{\pi}{10.16} * \cos 20^\circ$$

$$\rho_p = 21.37 \text{ mm}$$

$$\rho_g = c \sin \phi \mp \rho_p = (62.5 + 75) * \sin 20^\circ - 21.37$$

$$\rho_g = 25.7 \text{ mm}$$

$$I_{\text{idler(pinion)}} = \frac{\cos \phi}{\left(\frac{1}{21.37} + \frac{1}{25.7}\right) * 62.5} = 0.175$$

The surface stress for pinion-idler mesh:

$$\begin{aligned} \sigma_{cp} &= c_p \sqrt{\frac{\omega_t}{F * I_{\text{pinion}} * d_p} \frac{C_a * C_m * C_s * C_f}{C_v}} \\ &= 191 * \sqrt{\frac{0.546 * 10^3 \text{ N}}{30 * 0.115 * 50} \frac{1 * 1.6 * 1 * 1}{0.8}} \\ \sigma_{cp} &= 480.56 \text{ MPa} \end{aligned}$$

The surface stress for idler-gear mesh:

$$\sigma_{\text{idler}} = 191 * \sqrt{\frac{0.546 * 10^3}{30 * 0.175 * 62.5} \frac{1 * 1.6 * 1 * 1}{0.8}}$$

$$\sigma_{\text{idler}} = 348.4 \text{ MPa}$$

$$S_{f_c} = \frac{C_L * C_H}{C_T * C_R} * S'_{f_c}$$

$$S'_{f_c} \cong 820 \text{ MPa}$$

(for HB= 250 and Grade II) Table 11-27, page 737

$$C_T=1 \quad (T < 250^\circ \text{ F})$$

$$C_R=1 \quad (\%99 \text{ reliability})$$

$$C_H=1 \quad (\text{Hardness Ratio factor})$$

$$C_{L_{pinion}} = 1.4488N^{-0.023} = 1.4488(1.092 * 10^9)^{-0.023} \quad (\text{Fig. 11-26, pp.734})$$

$$= 0.898$$

$$C_{L_{idler}} = 0.917$$

$$C_{L_{gear}} = 0.92$$

$$S_{f_{c_{pinion}}} = 820 * 0.898 = 736 \text{ MPa}$$

$$S_{f_{c_{idler}}} = 752 \text{ MPa}$$

$$S_{f_{c_{gear}}} = 754 \text{ MPa}$$

$$N_{c_{pinion-idler}} = \left[\frac{736}{480.56} \right]^2 = 2.4$$

$$N_{c_{idler-gear}} = \left[\frac{752}{348.4} \right]^2 = 4.7$$

Hence; pinion-idler surface is more critical.

Note: we take the square of the safety factor because the surface stress is related to the square root of the load.