

MATH 107: Introduction to Linear Algebra

Midterm 1 - Spring 2020

Duration : 100 minutes

NAME _____

STUDENT ID _____

SIGNATURE _____

#1	20	
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- Put your name, student ID and signature in the space provided above.
- No calculators or any other electronic devices are allowed.
- This is a closed-book and closed-notes exam.
- Show all of your work; full credit will not be given for unsupported answers.
- Write your solutions clearly; no credit will be given for unreadable solutions.
- Mark your section below.

SECTION 1 (EMRE MENGI TuTh 13:00-14:15) _____

SECTION 2 (EMRE MENGI, MW 11:30-12:45) _____

SECTION 3 (EMRE MENGI, TuTh 8:30-9:45) _____

SECTION 4 (MEHMET SARIDERELI, TuTh 14:30-15:45) _____

SECTION 5 (AYBERK ZEYTIN, TuTh 8:30-9:45) _____

Solutions

Problem 1. (20 points) Let us consider a system of linear equations

$$Ax = b, \quad (1)$$

where $b \in \mathbb{R}^3$ and the coefficient matrix A is 3×5 . Moreover, A can be reduced to the echelon form

$$\begin{bmatrix} 1 & 2 & -1 & 0 & -3 \\ 0 & 0 & 1 & 1 & 4 \\ 0 & 0 & 0 & 1 & 3 \end{bmatrix}$$

by applying row operations, while the vector $p = [1 \ 2 \ 1 \ 1 \ 1]^T$ is a solution of the system of linear equations in (1), that is it satisfies $Ap = b$.

Write down the general solution of the system of linear equations in (1).

Find solution of $Ax = 0$ pivot positions

$$\left[\begin{array}{ccccc|c} 1 & 2 & -1 & 0 & -3 & 0 \\ 0 & 0 & 1 & 1 & 4 & 0 \\ 0 & 0 & 0 & 1 & 3 & 0 \end{array} \right] \xrightarrow[\substack{r_2 := r_2 - r_3 \\ r_1 := r_1 + r_2}]{\text{pivot positions}} \left[\begin{array}{ccccc|c} 1 & 2 & 0 & 0 & -2 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 3 & 0 \end{array} \right]$$

$x_1 \quad x_2 \quad x_3 \quad x_4 \quad x_5$

$$\begin{cases} x_2, x_5 \text{ are free} \\ x_4 = -3x_5, \quad x_3 = -x_5, \quad x_1 = -2x_2 + 2x_5 \end{cases}$$

Solution set for $Ax = 0$

$$S = \left\{ \begin{bmatrix} -2x_2 + 2x_5 \\ x_2 \\ -x_5 \\ -3x_5 \\ x_5 \end{bmatrix} \mid x_5 \in \mathbb{R} \right\} = \left\{ x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} 2 \\ 0 \\ -1 \\ -3 \\ 1 \end{bmatrix} \mid x_2, x_5 \in \mathbb{R} \right\}$$

Solution set for $Ax = b$

$$\begin{aligned} & \{ p + v \mid v \in S \} \\ &= \left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \\ 1 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} 2 \\ 0 \\ -1 \\ -3 \\ 1 \end{bmatrix} \mid x_2, x_5 \in \mathbb{R} \right\} \end{aligned}$$

Problem 2. (20 points) Find the values of $a, b \in \mathbb{R}$ so that

$$\begin{bmatrix} 3 \\ -1 \\ 2 \\ 2 \end{bmatrix} \in \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -2 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ a \\ b \\ 4 \end{bmatrix} \right\}.$$

Find $a, b \in \mathbb{R}$ such that

$$(+)\quad c_1 \begin{bmatrix} 1 \\ 2 \\ 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 1 \\ -2 \\ 2 \end{bmatrix} + c_3 \begin{bmatrix} 1 \\ a \\ b \\ 4 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \\ 2 \\ 2 \end{bmatrix}$$

$$\iff \begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & a \\ 1 & -2 & b \\ 1 & 2 & 4 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \\ 2 \\ 2 \end{bmatrix}$$

has a solution c_1, c_2, c_3 .

Now reduce the augmented matrix (by applying row operations)

$$\left[\begin{array}{ccc|c} 1 & 1 & 1 & 3 \\ 2 & 1 & a & -1 \\ 1 & -2 & b & 2 \\ 1 & 2 & 4 & 2 \end{array} \right] \xrightarrow{\substack{\Gamma_2 \ominus = \Gamma_2 - 2\Gamma_1 \\ \Gamma_3 \ominus = \Gamma_3 - \Gamma_1 \\ \Gamma_4 \ominus = \Gamma_4 - \Gamma_1}} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 3 \\ 0 & -1 & a-2 & -7 \\ 0 & -3 & b-1 & -1 \\ 0 & 1 & 3 & -1 \end{array} \right]$$

$$\xrightarrow{\substack{\Gamma_3 \ominus = \Gamma_3 - 3\Gamma_2 \\ \Gamma_4 \ominus = \Gamma_4 + \Gamma_2}} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 3 \\ 0 & -1 & a-2 & -7 \\ 0 & 0 & b-3a+5 & 20 \\ 0 & 0 & a+1 & -8 \end{array} \right]$$

$$\left(\text{assuming } b-3a+5 \neq 0 \right) \xrightarrow{\Gamma_4 \ominus = \Gamma_4 - \frac{(a+1)}{b-3a+5} \Gamma_3} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 3 \\ 0 & -1 & a-2 & -7 \\ 0 & 0 & b-3a+5 & 20 \\ 0 & 0 & 0 & -8 - \frac{a+1}{b-3a+5} 20 \end{array} \right]$$

It follows that (+) has a solution if and only if

$$b-3a+5 \neq 0 \quad \text{and} \quad 8 + \frac{a+1}{b-3a+5} 20 = 0$$

$$\text{(plug in } a=2b+15 \text{ to obtain } -5b-40 \neq 0)$$

$$\iff -2(b-3a+5) = 5(a+1)$$

$$\iff a = 2b+15 \quad \textcircled{1}$$

that is (+) has a solution if and only if

$$a = 2b+15 \quad \text{and} \quad b \neq -8$$

Problem 3. Let T be the linear transformation defined by

$$T: \mathbb{R}^3 \rightarrow \mathbb{R}^3, \quad T \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right) = \begin{bmatrix} x_1 + 2x_2 + 3x_3 \\ x_2 + 2x_3 \\ x_3 \end{bmatrix}.$$

When answering parts (a) and (b) below, explain your reasoning.

(a) (8 points) Is T one-to-one?

Standard matrix of T

$$(*) \quad A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

Check whether $Ax=0$ has a nontrivial solution.

$$\left[\begin{array}{ccc|c} 1 & 2 & 3 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right] \xrightarrow{\substack{r_2 := r_2 - 2r_3 \\ r_1 := r_1 - 3r_3 \\ r_1 := r_1 - 2r_2}} \left[\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right]$$

No, the only solution is $x=0$, so the columns of A are linearly independent. This implies T is one-to-one.

(b) (7 points) Is T onto?

Since every row of A in (*) has a pivot position,

$Ax=b$ has a solution for all b .

$\overbrace{T(x)}^{T(x)}$ This implies T is onto.

Problem 4.

- (a) (5 points) Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a one-to-one, onto linear transformation with the standard matrix M , and $T^{-1} : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be the inverse of T with the standard matrix N . How are the matrices M and N related?

$$MN = I_n \quad \text{and} \quad NM = I_n$$

- (b) (20 points) Let $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be the linear transformation such that

$$T\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}, \quad T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}, \quad T\left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}.$$

Find the standard matrix of $T^{-1}(x)$.

$$T(x) = Ax, \quad \text{where}$$

$$A = \begin{bmatrix} T\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) & T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) & T\left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right) \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 2 & 1 \\ -1 & 0 & 1 \\ 1 & 1 & 3 \end{bmatrix}$$

Then $T^{-1}(x) = A^{-1}x$, that is A^{-1} is the standard matrix of T^{-1} .

Computation of A^{-1}

$$\left[\begin{array}{ccc|ccc} 1 & 2 & 1 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 & 1 & 0 \\ 1 & 1 & 3 & 0 & 0 & 1 \end{array} \right]$$

$A \qquad I_3$

$$\xrightarrow{\substack{r_2 := r_2 + r_1 \\ r_3 := r_3 - r_1}} \left[\begin{array}{ccc|ccc} 1 & 2 & 1 & 1 & 0 & 0 \\ 0 & 2 & 2 & 1 & 1 & 0 \\ 0 & -1 & 2 & -1 & 0 & 1 \end{array} \right]$$

$$\xrightarrow{r_3 := r_3 + \frac{1}{2}r_2} \left[\begin{array}{ccc|ccc} 1 & 2 & 1 & 1 & 0 & 0 \\ 0 & 2 & 2 & 1 & 1 & 0 \\ 0 & 0 & 3 & -1/2 & 1/2 & 1 \end{array} \right]$$

$$\xrightarrow{r_3 := (1/3)r_3} \left[\begin{array}{ccc|ccc} 1 & 2 & 1 & 1 & 0 & 0 \\ 0 & 2 & 2 & 1 & 1 & 0 \\ 0 & 0 & 1 & -1/6 & 1/6 & 1/3 \end{array} \right]$$

$$\xrightarrow{\substack{r_2 := r_2 - 2r_3 \\ r_1 := r_1 - r_3}} \left[\begin{array}{ccc|ccc} 1 & 2 & 0 & 7/6 & -1/6 & -1/3 \\ 0 & 2 & 0 & 4/3 & 2/3 & -2/3 \\ 0 & 0 & 1 & -1/6 & 1/6 & 1/3 \end{array} \right]$$

$$\xrightarrow{\substack{r_2 := (1/2)r_2 \\ r_1 := r_1 - 2r_2}} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & -1/6 & -5/6 & 1/3 \\ 0 & 1 & 0 & 2/3 & 1/3 & -1/3 \\ 0 & 0 & 1 & -1/6 & 1/6 & 1/3 \end{array} \right]$$

$$A^{-1} = \begin{bmatrix} -1/6 & -5/6 & 1/3 \\ 2/3 & 1/3 & -1/3 \\ -1/6 & 1/6 & 1/3 \end{bmatrix}$$

is the standard matrix of T^{-1} .

Problem 5. Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation, and $\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_k \in \mathbb{R}^n$ be given vectors.

- (a) (15 points) Show that if $\{T(\mathbf{a}_1), T(\mathbf{a}_2), \dots, T(\mathbf{a}_k)\}$ is linearly independent, then $\{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_k\}$ is also linearly independent.

Suppose

$$c_1 \mathbf{a}_1 + \dots + c_k \mathbf{a}_k = \mathbf{0}$$

for some $c_1, \dots, c_k \in \mathbb{R}$.

But then by linearity of T

$$T(c_1 \mathbf{a}_1 + \dots + c_k \mathbf{a}_k) = T(\mathbf{0}) = \mathbf{0}$$

and

$$c_1 T(\mathbf{a}_1) + \dots + c_k T(\mathbf{a}_k) = \mathbf{0}.$$

Since $\{T(\mathbf{a}_1), \dots, T(\mathbf{a}_k)\}$ is linearly independent, we have $c_1 = c_2 = \dots = c_k = 0$, proving that $\{\mathbf{a}_1, \dots, \mathbf{a}_k\}$ is linearly independent.

- (b) (5 points) Prove or disprove the following statement:

- If $\{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_k\}$ is linearly independent, then $\{T(\mathbf{a}_1), T(\mathbf{a}_2), \dots, T(\mathbf{a}_k)\}$ is also linearly independent.

(Note: To prove the statement, you must show its validity for every linear transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ and every $\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_k \in \mathbb{R}^n$. To disprove, it is sufficient to give one counter example.)

Consider

$$T : \mathbb{R}^2 \rightarrow \mathbb{R}^2, \quad T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} x_1 \\ 0 \end{bmatrix}.$$

The set

$$\left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$$

is clearly independent, but

$$\left\{ T\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right), T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) \right\} = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$$

is linearly dependent.

This shows that the statement is false.