

LECTURE 10INEXACT LINE SEARCH

To define sufficient decrease condition we again use the linear approximation

$$\begin{aligned} l(\alpha) &= \phi(0) + \alpha \phi'(0) \\ &= f(x_k) + \alpha \nabla f(x_k)^T p_k \end{aligned}$$

where

$$\phi(\alpha) = f(x_k + \alpha p_k).$$

THM: Suppose $\phi'(0) \neq 0$. Then

$$\lim_{\alpha \rightarrow 0} \frac{\phi(0) - \phi(\alpha)}{l(0) - l(\alpha)} = 1$$

PROOF

By Taylor's thm

$$\phi(\alpha) = \phi(0) + \alpha \phi'(0) + \frac{\alpha^2}{2} \phi''(t)$$

where $t \in (0, \alpha)$.

~~But then~~

~~$$\lim_{\alpha \rightarrow 0} -\alpha \phi'(0) - \frac{\alpha^2}{2}$$~~

But then

$$\lim_{\alpha \rightarrow 0} \frac{\phi(0) - \phi(\alpha)}{l(0) - l(\alpha)} =$$
$$\lim_{\alpha \rightarrow 0} \frac{-\alpha \phi'(0) - (\cancel{\alpha^2/2}) \phi''(t)}{-\alpha \phi'(0)} = 1$$

□

Therefore for any $M \in (0, 1)$

$$\boxed{\frac{\phi(0) - \phi(\alpha)}{l(0) - l(\alpha)} \geq M}$$

for all $\alpha > 0$ sufficiently close to 0.

Equivalently for all $\alpha > 0$ close to 0

$$\phi(0) - \phi(\alpha) \geq M(l(0) - l(\alpha))$$

$$\implies \phi(0) - \phi(\alpha) \geq M(-\alpha \phi'(0))$$

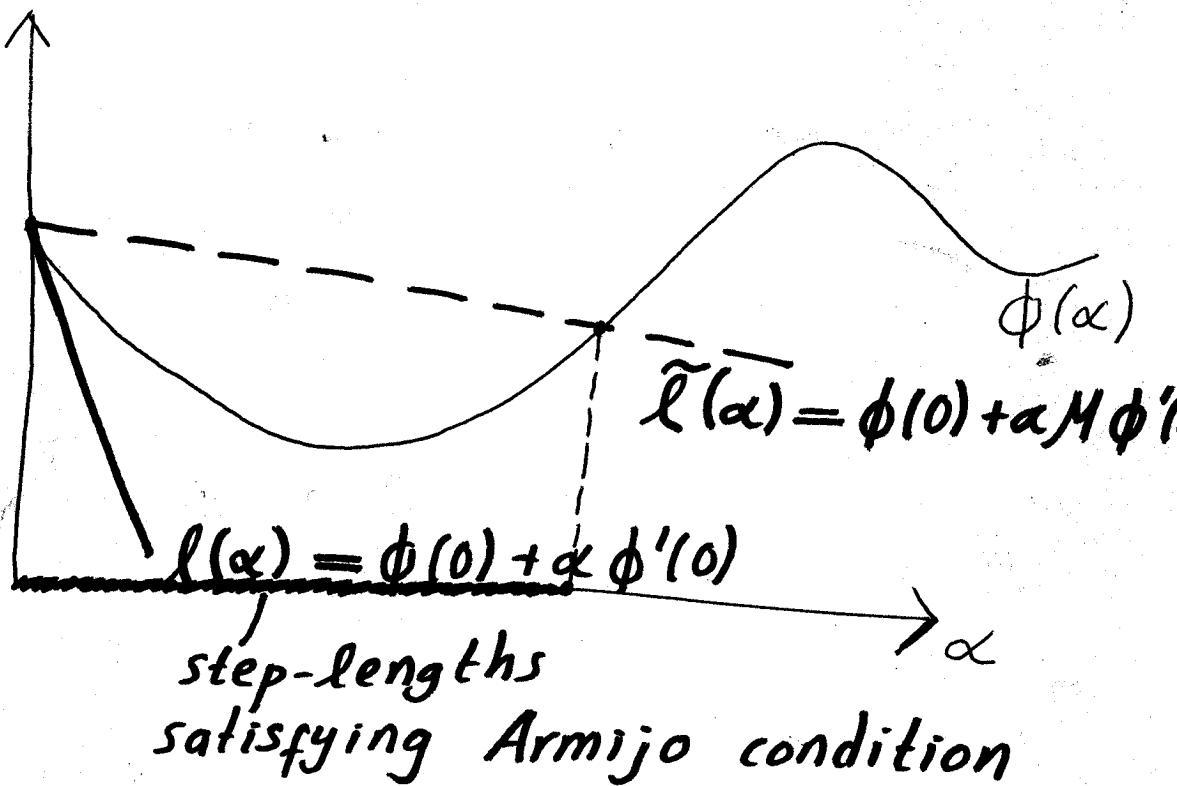
$$\implies \underbrace{\phi(0) + M\alpha \phi'(0)}_{\tilde{l}(\alpha)} \geq \phi(\alpha)$$

$$\implies f(x_k) + M\alpha \nabla f(x_k)^T p_k \geq f(x_k + \alpha p_k)$$

②

ARMIJO SUFFICIENT DECREASE CONDITION

$$f(x_k) + \alpha M \nabla f(x_k)^T p_k \geq f(x_k + \alpha p_k)$$



In Goldstein-Armijo backtracking line search we start with $\alpha = 1$ and halve α until Armijo condition is satisfied.

ALGORITHM (Goldstein-Armijo backtracking line search)

Given $x_k, p_k \in \mathbb{R}^n$, $\alpha_k = 1$

while $f(x_k + \alpha_k p_k) > f(x_k) + \alpha_k M \nabla f(x_k)^T p_k$

$\alpha_k = \alpha_k / 2$

end

return α_k

GENERATION OF A DESCENT DIRECTION

Basic idea

- * Represent $f(x)$ by a quadratic approximation $Q(x)$ about x_k .
- * Find the local minimizer x_* of $Q(x)$.
- * Define $p_k := x_* - x_k$

Quadratic Approximation

By Taylor's thm

$$f(x) = f(x_k) + \nabla f(x_k)^T (x - x_k) + \frac{1}{2} (x - x_k)^T \nabla^2 f(x_k + t(x - x_k)) (x - x_k)$$

for some $t \in (0, 1)$.

Approximate f by

$$Q(x) = f(x_k) + \nabla f(x_k)^T (x - x_k) + \frac{1}{2} (x - x_k)^T B_k (x - x_k)$$

where B_k is symmetric.

Assume $B_k > 0$. Local minimizer x_* of $Q(x)$ satisfies

$$0 = \nabla Q(x_*) = \nabla f(x_k) + B_k(x_* - x_k)$$

$$\implies$$

$$B_k(x_* - x_k) = -\nabla f(x_k)$$

Search direction p_k satisfies

$$\boxed{B_k p_k = -\nabla f(x_k)}$$

equivalently

$$\boxed{p_k = -B_k^{-1} \nabla f(x_k)}$$

STEEPEST DESCENT

Choose $B_k = I$, i.e.

$$Q(x) = f(x_k) + \nabla f(x_k)^T (x - x_k) + \frac{1}{2} (x - x_k)^T (x - x_k)$$

Then the steepest descent direction
 $p_k^{SD} = -\nabla f(x_k)$

NEWTON'S METHOD

Choose $B_k = \nabla^2 f(x_k)$, i.e.

$$Q(x) = f(x_k) + \nabla f(x_k)^T (x - x_k) + \frac{1}{2} (x - x_k)^T \nabla^2 f(x_k) (x - x_k)$$

Then the Newton direction satisfies

$$\nabla^2 f(x_k) p_k^N = -\nabla f(x_k)$$

equivalently

$$p_k^N = -\nabla^2 f(x_k)^{-1} \nabla f(x_k)$$

EXAMPLE

$$f(x) = x_2 e^{x_1} \quad \text{at} \quad x_k = (0, 0)$$

Gradient

$$\nabla f(x) = \begin{bmatrix} x_2 e^{x_1} \\ e^{x_1} \end{bmatrix}, \quad \nabla f(x_k) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Hessian

$$\nabla^2 f(x) = \begin{bmatrix} x_2 e^{x_1} & e^{x_1} \\ e^{x_1} & 0 \end{bmatrix}, \quad \nabla^2 f(x_k) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

Steepest descent direction

$$P_k^{SD} = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

Newton direction satisfies

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} P_k^N = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

$$\Rightarrow P_k^N = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

Steepest descent direction is a
descent direction

$$\nabla f(x_k)^T P_k^{SD} = -1 < 0$$

Newton direction is not a descent
direction

$$\nabla f(x_k)^T P_k^N = 0$$

THM

Suppose $B_k \succ 0$. Then the direction p_k such that $\nabla Q(p_k) = 0$ is a descent direction.

PROOF

Notice that

$$B_k \succ 0 \iff B_k^{-1} \succ 0 \quad (\text{see remarks below})$$

Consequently

$$\nabla f(x_k)^T p_k = -\nabla f(x_k)^T B_k^{-1} \nabla f(x_k) < 0$$
□

REMARK

$$* Ax = \lambda x \iff A^{-1}x = (1/\lambda)x$$

* λ is an eigenvalue of A

\iff
 $(1/\lambda)$ is an eigenvalue of A^{-1}

e.g.

$$A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

eigvals $\lambda_1=3, \lambda_2=1$

(i.e. $AA^{-1}=I$)

$$A^{-1} = \begin{bmatrix} 2/3 & -1/3 \\ -1/3 & 2/3 \end{bmatrix}$$

eigvals $\lambda_1=1/3, \lambda_2=1$

* Consequently

$$A \succ 0 \iff A^{-1} \succ 0$$

Both $A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$ and $A^{-1} = \begin{bmatrix} 2/3 & -1/3 \\ -1/3 & 2/3 \end{bmatrix}$
are positive definite.